

GLOBAL EXISTENCE OF SOLUTIONS FOR A FREE BOUNDARY PROBLEM OF HYPERBOLIC TYPE WITH NON CONSTANT ADHESION

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Abstract. A free boundary problem which arises from the physical model “Peel a thin film from a domain” is treated. The behavior of the peeling front is governed by the hyperbolic equation. If we suppose the effect Q from the peeling front to Lagrangian is constant, the global solution have been constructed by pasting the local solutions inductively. In this note, the case where Q is a function of the space is treated. Because the effect from peeling front is supposed to depend on the situation of the domain. If we impose a regularity condition on Q , the sufficient condition for the global existence of the solution is given.

Key words. free boundary, hyperbolic equation, variational problem

AMS subject classifications. 35R35, 35L70

1. Introduction. Let us consider the following one-dimensional free boundary problem

$$(P) \quad \begin{cases} u_{xx} - u_{tt} = 0 & \text{in } (0, \infty) \times \{t > 0\} \cap \{u > 0\}, \\ u_x^2 - u_t^2 = Q^2 & \text{on } (0, \infty) \times \{t > 0\} \cap \partial\{u > 0\}, \end{cases}$$

with the initial conditions

$$(I) \quad \begin{cases} u(x, 0) = e(x) & \text{in } (-l_0, 0), \\ u_t(x, 0) = g(x) & \text{in } (-l_0, 0), \end{cases}$$

and the boundary condition

$$(B) \quad u(-l_0, t) = f(t) \quad \text{for } t \geq 0,$$

where $e(x)$, $g(x)$, $f(t)$ and Q are given functions, and l_0 is a positive constant.

This problem arises from the following variational problem which is related to a physical model “Peel a thin film from a domain Ω ” (cf. [7]). The shape of a film is described by the graph of a function $u : \Omega \rightarrow \mathbf{R}$. Find a stationary point of the functional

$$(1.1) \quad J(u) := \int_0^{T^*} \int_{\Omega} \left(\frac{\tau}{2} |\nabla u|^2 - \frac{\rho}{2} (D_t u)^2 \chi_{u>0} + \frac{Q^2}{2\tau} \chi_{u>0} \right) dx dt \quad u \in K,$$

where Ω is a domain in \mathbf{R}^n , T^* is a positive constant, $\chi_{u>0}$ is a characteristic function of the set $\{(x, t) \in \Omega \times (0, T^*); u(x, t) > 0\}$ and K is a suitable function space. Here the

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constants τ , ρ are the tension and the line density, and Q is the adhesion. To approach this problem, we assume that a stationary point is sufficiently smooth. Then we can derive (1.2) and (1.3) as the Euler-Lagrange equations from the functional (1.1) (cf. [1], [2] and [4]),

$$(1.2) \quad \tau \Delta u - \rho u_{tt} = 0 \quad \text{in } \Omega \times \{t > 0\} \cap \{u > 0\},$$

$$(1.3) \quad \frac{\tau}{2} |\nabla u|^2 - \frac{\rho}{2} u_t^2 = \frac{Q^2}{2\tau} \quad \text{on } \Omega \times \{t > 0\} \cap \partial\{u > 0\}.$$

In this article, as a first step, a one-dimensional problem will be analyzed. By using some change of variable t , $\tau = 1$ and $\rho = 1$ can be assumed. Therefore, we will consider the problem (P) , (I) and (B) .

The initial condition (I) implies that a thin film has been already peeled from the plate on the interval $(-l_0, 0)$ and the boundary condition (B) corresponds to the situation in which the edge of film is lifted up by $f(t)$. Kikuchi and Omata [4] showed the existence of time-local solutions under the several conditions which were imposed on the functions $e(x)$, $g(x)$ and $f(t)$. On the global existence of solutions, however, they have not stated.

In the case of Q is constant, numerical experiments were carried out in [3]. A sufficient condition for the global existence was given in [6]. That is to say, the solution can be constructed by pasting the local solutions inductively, if $f' \geq 0$, the solution can be extended to any $T > 0$. And the same time, by using the expression of the solution of this way, a well-posedness can be shown and the periodic solutions are constructed.

In this note, the case where Q is a function of the space is treated, namely, it is given on the line $\{(x, t); t = 0\}$. Because the effect Q from the peeling front to the Lagrangian is supposed to depend on the situation of the domain. If we impose a condition (A.5) on Q , then the global solution can be constructed.

2. Construction of solutions. To prove our problem, two variables ξ and η are introduced by

$$\begin{aligned} t &= (\xi + \eta)/2, \\ x &= (\xi - \eta)/2. \end{aligned}$$

Since the initial values e and g are given on the line $\{(x, t); t = 0\}$, they are given on the line $\{(\xi, \eta); \xi + \eta = 0\}$. We regard them as the functions of ξ and rewrite them e and g again. Similarly, the boundary value f and the adhesion Q are given on the line $\{(\xi, \eta); \xi - \eta + 2l_0 = 0\}$ and $\{(x, t); t = 0\}$, respectively. They are functions of η . Therefore (P) , (I) and (B) are transformed into

$$(P') \quad \begin{cases} u_{\xi\eta} = 0 & \text{in } \{u > 0\}, \\ -4u_{\xi}u_{\eta} = Q^2(\eta) & \text{on } \partial\{u > 0\}, \end{cases}$$

$$(I') \quad \begin{cases} u(\xi, -\xi) = e(\xi) & \text{in } (-l_0, 0), \\ u_{\eta}(\xi, -\xi) + u_{\xi}(\xi, -\xi) = g(\xi) & \text{in } (-l_0, 0), \end{cases}$$

$$(B') \quad u(\eta - 2l_0, \eta) = f(\eta - l_0) \quad \text{in } [l_0, \infty).$$

By taking these equations into considerations, we treat the following problem:

Problem 2.1 Let T be a positive constant. Find a pair of functions $u \in C^0(\{(\xi, \eta); \xi \geq \eta - 2l_0, \xi \geq -\eta\})$ and $l \in C^0([0, T]) \cap C^1((0, T))$ which satisfies (P') , (I') and (B') for $\eta < T$ and

- (i) $l(0) = 0$,
- (ii) $u \in C^2(\{(\xi, \eta); \eta - 2l_0 < \xi < l(\eta), \xi > -\eta\}) \cap C^1(\{(\xi, \eta); \eta - 2l_0 < \xi \leq l(\eta), \xi \geq -\eta\})$,
- (iii) $u > 0$ in $\{(\xi, \eta); \eta - 2l_0 \leq \xi < l(\eta), \xi > -\eta\}$,
- (iv) $u(\xi, \eta) = 0$ in $\{(\xi, \eta); \xi \geq l(\eta)\} \cup \{(\xi, \eta); \xi \geq -\eta, \eta < 0\}$.

Assumption 2.1 The functions $f(\eta - l_0) \in C^2([l_0, \infty))$, $e(\xi) \in C^2([-l_0, 0])$, $g(\xi) \in C^1([-l_0, 0])$ and $Q(\eta) \in C^0([0, \infty))$ satisfy

$$(A.0) \quad \begin{cases} e(\xi) > 0 & \text{in } (-l_0, 0), \\ g(\xi) > 0 & \text{in } (-l_0, 0), \end{cases}$$

$$(A.1) \quad \begin{cases} f(0) = e(-l_0) > e(0) = 0, \\ f'(0) = g(-l_0), \\ f''(0) = e''(-l_0), \end{cases}$$

$$(A.2) \quad \begin{cases} e(0) = 0, \\ e'(0)^2 - g(0)^2 = Q^2(0), \\ -Q^3(0)\{2Q'(0)(-e'(0) + g(0)) - Q(0)(e''(0) - g'(0))\} \\ = (-e'(0) + g(0))^4(e''(0) + g''(0)), \end{cases}$$

$$(A.3) \quad \begin{cases} e'(\xi) < g(\xi) & \text{for } (-l_0 \leq \xi \leq 0), \\ f'(\xi + l_0) - (e'(\xi) + g(\xi))/2 > 0 & \text{for } (-l_0 \leq \xi \leq 0), \end{cases}$$

$$(A.4) \quad f'(\eta - l_0) \geq 0 \quad \text{for } \eta \in [l_0, \infty).$$

$$(A.5) \quad Q \text{ is locally monotone function, i.e. for any } \eta_0 \\ \text{there is a constant } \delta(\eta_0) > 0 \text{ such that } Q(\eta_1) \leq Q(\eta_2) \text{ or} \\ Q(\eta_1) \geq Q(\eta_2) \text{ for all } \eta_1, \eta_2 \in [\eta_0 - \delta(\eta_0), \eta_0] \text{ with } \eta_1 \leq \eta_2.$$

Remark 2.1 (i) (A.1) is a compatible condition on the lifting edge and (A.2) is a condition on the peeling front at $t = 0$. From our physical model, it is easy to see that the singularities start from these points and they propagate along the lines which run parallel to the (η, ξ) -axes. To show the regularity of the solution, we need to impose some conditions on them. If the first equations of (A.1) and (A.2) are satisfied, we can show the solution is continuous. By using direct calculation, the second one and third one guarantee C^1 and C^2 regularity of the solution, respectively.

(ii) (A.3) is assumed by the technical reason. We may consider (A.3) is consistent with the domain of dependence, however, we do not know the relation between them.

(iii) (A.4) and (A.5) are needed to construct global solutions. Even if Q belongs to C^k class for any $k > 0$, there is an example such that it does not enjoy (A.5) ($x^k \sin \frac{1}{x}$ is not locally monotone at 0). However, (A.5) is satisfied by the function which has no point where the signature of the Q' changes infinity many time in its neighborhood.

The following procedure is originally given in [4]. To confirm the global existence of the solution, we will modify its proof and introduce an iteration method.

Lemma 2.1 *Let c be a positive number and $I = [0, c)$ an interval on the axis η . Let $Q(\eta) \in C^0([0, \infty))$ and $\lambda(\eta) \in C^2(I)$ be a function which satisfies*

- (i) $\lambda(0) = 0$,
(ii) $\lambda'(\eta) > 0$ on $\eta \in I$.

Then there exists a unique pair of functions $u(\xi, \eta) \in C^2(\{(\xi, \eta); \eta \in I, 0 < \xi < l(\eta)\}) \cap C^1(\{(\xi, \eta); \eta \in I, 0 \leq \xi \leq l(\eta)\})$ and $l(\eta) \in C^2(I)$ such that

$$(PL) \begin{cases} u_{\xi\eta} = 0 & \text{in } \{(\xi, \eta); 0 < \xi < l(\eta), \eta \in I\}, \\ -4u_{\xi}u_{\eta} = Q^2(\eta) & \text{on } (l(\eta), \eta), \eta \in I, \\ u(l(\eta), \eta) = 0 & \text{on } \eta \in I, \\ u(0, \eta) = \lambda(\eta) & \text{on } \eta \in I. \end{cases}$$

Proof. At first, let us define the functions ψ and l by

$$\begin{aligned} \psi(\eta) &= \lambda(\eta), \\ l(\eta) &= 4 \int_0^{\eta} \frac{\psi'(s)^2}{Q^2(s)} ds. \end{aligned}$$

Because ψ' is positive, $l^{-1}(\xi)$ exists in $[0, l(c))$. The function ϕ is defined by

$$\phi(\xi) = -\psi(l^{-1}(\xi)).$$

Then we can see that $u(\xi, \eta) = \phi(\xi) + \psi(\eta)$ and $l(\eta)$ are desired functions.

Nextly, we show the uniqueness of the solution. Suppose that there exist another functions $(\tilde{u}(\xi, \eta), \tilde{l}(\eta))$ satisfying (PL) which has the form $\tilde{u}(\xi, \eta) = \tilde{\phi}(\xi) + \tilde{\psi}(\eta)$. It follows that

$$(2.1) \quad \tilde{u}(\tilde{l}(\eta), \eta) = 0.$$

From the fact $-4\tilde{u}_{\xi}\tilde{u}_{\eta} = Q^2$ and by differentiating the both sides of (2.1) with respect to η , we have

$$\tilde{l}'(\eta) = \frac{4}{Q^2(\eta)} \tilde{\psi}'(\eta)^2.$$

Since the free boundary starts at origin, we obtain

$$\tilde{l}(\eta) = 4 \int_0^{\eta} \frac{\tilde{\psi}'(s)^2}{Q^2(s)} ds.$$

Because of

$$\tilde{u}(0, \eta) = \tilde{\phi}(0) + \tilde{\psi}(\eta) = \lambda(\eta),$$

it follows

$$\tilde{\psi}'(\eta) = \lambda'(\eta).$$

It implies that \tilde{l} is equal to l . Hence, from Goursat's theorem, $(\tilde{u}(\xi, \eta), \tilde{l}(\eta))$ coincides with $(u(\xi, \eta), l(\eta))$, it is a contradiction proving our assertion. ■

Main Theorem *For any $T > 0$, there exists a unique solution to Problem 2.1.*

Proof. Firstly, let ϕ_0 and ψ_1 be functions such that

$$\begin{cases} \phi_0(\xi) = \frac{1}{2} \left(e(\xi) + \int_0^\xi g(s) ds \right) & \text{for } -\lambda_1 \leq \xi \leq 0, \\ \psi_1(\eta) = \frac{1}{2} \left(e(-\eta) + \int_{-\eta}^0 g(s) ds \right) & \text{for } 0 \leq \eta < \lambda_1, \end{cases}$$

where $\lambda_1 = l_0$. Evidently, $u(\xi, \eta) = \phi_0(\xi) + \psi_1(\eta)$ is a unique solution to the initial value problem in $\{(\xi, \eta); -l_0 < -\eta < \xi < 0\}$. Let us define the free boundary l_1 by

$$l_1(\eta) = 4 \int_0^\eta \frac{\psi_1'(s)^2}{Q^2(s)} ds.$$

By (A.3), $\psi_1'(\eta)$ is positive for $0 \leq \eta < \lambda_1$. Therefore there exists $l_1^{-1}(\xi)$ for $0 \leq \xi < l_1(\lambda_1)$ and we can define ϕ_1 by

$$\phi_1(\xi) = -\psi_1(l_1^{-1}(\xi)) \quad \text{for } 0 \leq \xi < l_1(\lambda_1).$$

By using these functions, we define the functions u and l by

$$u(\xi, \eta) = \begin{cases} \phi_0(\xi) + \psi_1(\eta) & \text{on } D_{0,1}, \\ \phi_1(\xi) + \psi_1(\eta) & \text{on } D_{1,1}, \\ 0 & \text{on } D_{e,1}, \end{cases}$$

$$l(\eta) = l_1(\eta) \quad \text{for } \{\eta; 0 \leq \eta < \lambda_1\},$$

where

$$\begin{aligned} D_{0,1} &= \{(\xi, \eta); \xi \geq -\eta, -l_0 \leq \xi < 0, 0 \leq \eta < \lambda_1\}, \\ D_{1,1} &= \{(\xi, \eta); 0 \leq \xi < l_1(\eta), 0 \leq \eta < \lambda_1\}, \\ D_{e,1} &= \{(\xi, \eta); \xi \geq l_1(\eta), 0 \leq \eta < \lambda_1, \}. \end{aligned}$$

The regularity on the joint line $\xi = 0$ of ϕ_0 and ϕ_1 is guaranteed by (A.2). By Lemma 2.1, $(u(\xi, \eta), l(\eta))$ is a unique solution to Problem 2.1 on $D_{0,1} \cup D_{1,1} \cup D_{e,1}$.

Nextly, we define ψ_2 by

$$\psi_2(\eta) = \begin{cases} f(\eta - l_0) - \phi_0(\eta - 2l_0) & \text{for } \lambda_1 \leq \eta < 2\lambda_1, \\ f(\eta - l_0) - \phi_1(\eta - 2l_0) & \text{for } 2\lambda_1 \leq \eta < \lambda_2, \end{cases}$$

where $\lambda_2 = l_1(\lambda_1) + 2l_0$. Since ϕ_0 and ϕ_1 are connected smoothly, $\psi_2(\eta)$ is of C^2 -class. Because the free boundary starts from $l_1(\lambda_1)$, l_2 is defined by

$$l_2(\eta) = 4 \int_{\lambda_1}^\eta \frac{\psi_2'(s)^2}{Q^2(s)} ds + l_1(\lambda_1) \quad \text{for } \lambda_1 \leq \eta < \lambda_2.$$

Obviously, l_2 is of C^2 -class. By (A.3) and (A.4), $\psi_2'(\eta) > 0$ holds on $[\lambda_1, \lambda_2)$. Then there exists $l_2^{-1}(\xi)$ for $l_2(\lambda_1) \leq \xi < l_2(\lambda_2)$. Hence we can define

$$\phi_2(\xi) = -\psi_2(l_2^{-1}(\xi)) \quad \text{for } l_2(\lambda_1) \leq \xi < l_2(\lambda_2).$$

The functions $(u(\xi, \eta), l(\eta))$ are extended as the following

$$u(\xi, \eta) = \begin{cases} \phi_0(\xi) + \psi_2(\eta) & \text{on } D_{0,2}, \\ \phi_1(\xi) + \psi_2(\eta) & \text{on } D_{1,2}, \\ \phi_2(\xi) + \psi_2(\eta) & \text{on } D_{2,2}, \\ 0 & \end{cases}$$

$$l(\eta) = l_2(\eta) \quad \text{on } \{\eta; \lambda_1 \leq \eta < \lambda_2\},$$

where

$$\begin{aligned} D_{0,2} &= \{(\xi, \eta); \xi \geq \eta - 2l_0, -l_0 \leq \xi < 0, \lambda_1 \leq \eta < 2l_0\}, \\ D_{1,2} &= \{(\xi, \eta); \xi \geq \eta - 2l_0, 0 \leq \xi < l_1(\lambda_1), \lambda_1 \leq \eta < \lambda_2\}, \\ D_{2,2} &= \{(\xi, \eta); l_1(\lambda_1) \leq \xi < l_2(\eta), l_1 \leq \eta < \lambda_2\}, \\ D_{e,2} &= \{(\xi, \eta); \xi \geq l_2(\eta), \lambda_1 \leq \eta < \lambda_2\}. \end{aligned}$$

It follows from (A.1) that ψ_1 and ψ_2 , concurrently, ϕ_1 and ϕ_2 are connected smoothly on the line $\xi = \lambda_2 - 2l_0$. By applying Lemma 2.1 again, we can see the pair of functions $(u(\xi, \eta), l(\eta))$ is a unique solution to Problem 2.1.

Inductively, for $j \geq 3$, we define the functions ψ_j , l_j and ϕ_j by

$$\begin{aligned} \psi_j(\eta) &= f(\eta - l_0) - \phi_{j-1}(\eta - 2l_0) & \text{for } \lambda_{j-1} \leq \eta < \lambda_j, \\ l_j(\eta) &= 4 \int_{\lambda_{j-1}}^{\eta} \frac{\psi'_j(s)^2}{Q^2(s)} ds + l_{j-1}(\lambda_{j-1}) & \text{for } \lambda_{j-1} \leq \eta < \lambda_j, \\ \phi_j(\xi) &= -\psi_j(l_j^{-1}(\xi)) & \text{for } l_j(\lambda_{j-1}) \leq \xi < l_j(\lambda_j), \end{aligned}$$

where

$$\lambda_j = l_{j-1}(\lambda_{j-1}) + 2l_0.$$

Suppose that it has been already shown that $\psi_{j-1}(\eta)$, $l_{j-1}(\eta)$ and $\phi_{j-1}(\xi)$ are well-defined and of C^2 -class, and $\psi'_{j-1}(\eta) > 0$ on $\lambda_{j-2} \leq \eta < \lambda_{j-1}$. In addition, it is supposed that ϕ_{j-2} and ϕ_{j-1} are connected smoothly on the line $\xi = \lambda_{j-1} - 2l_0$. Since

$$\begin{aligned} (2.2) \quad \lambda_j - \lambda_{j-1} &= 4 \int_{\lambda_{j-2}}^{\lambda_{j-1}} \frac{\psi'_{j-1}(s)^2}{Q^2(s)} ds \\ &\geq 4 \left(\min_{\lambda_{j-2} \leq \eta < \lambda_{j-1}} \frac{\psi'_{j-1}(\eta)}{Q(\eta)} \right)^2 (\lambda_{j-1} - \lambda_{j-2}), \end{aligned}$$

holds, we have $\lambda_j > \lambda_{j-1}$. Here we remark that $l_j(\lambda_{j-1}) = l_{j-1}(\lambda_{j-1})$. It can be seen that ψ_j and l_j are well-defined and of C^2 -class, immediately. We have

$$\begin{aligned} \psi'_j(\eta) &= f'(\eta - l_0) - \phi'_{j-1}(\eta - 2l_0) \\ &= f'(\eta - l_0) + \frac{1}{4} \frac{Q^2(l_{j-1}^{-1}(\eta - 2l_0))}{\psi'_{j-1}(l_{j-1}^{-1}(\eta - 2l_0))}, \end{aligned}$$

it follows $\psi'_j(\eta) > 0$ on $\lambda_{j-1} \leq \eta < \lambda_j$ by (A.4) and induction assumption. Therefore, there exists l_j^{-1} for $l_j(\lambda_{j-1}) \leq \xi < l_j(\lambda_j)$, and it implies that ϕ_j is well-defined and

of C^2 -class. From the induction assumption, ψ_{j-1} and ψ_j are connected smoothly on the line $\eta = \lambda_{j-1}$. Therefore ϕ_{j-1} and ϕ_j are connected smoothly on the line $\xi = \lambda_j - 2l_0$. By combining these functions, the pair of functions $(u(\xi, \eta), l(\eta))$ can be extended as the following

$$u(\xi, \eta) = \begin{cases} \phi_{j-1}(\xi) + \psi_j(\eta) & \text{on } D_{j-1,j}, \\ \phi_j(\xi) + \psi_j(\eta) & \text{on } D_{j,j}, \\ 0 & \text{on } D_{e,j}, \end{cases}$$

$$l(\eta) = l_j(\eta) \quad \text{for } \{\eta; \lambda_{j-1} \leq \eta < \lambda_j\},$$

where

$$\begin{aligned} D_{j-1,j} &= \{(\xi, \eta); \xi \geq \eta - 2l_0, \lambda_{j-1} - 2l_0 \leq \xi < l_{j-1}(\lambda_{j-1}), \lambda_{j-1} \leq \eta < \lambda_j\}, \\ D_{j,j} &= \{(\xi, \eta); l_{j-1}(\lambda_{j-1}) \leq \xi < l_j(\eta), \lambda_{j-1} \leq \eta < \lambda_j\}, \\ D_{e,j} &= \{(\xi, \eta); \xi \geq l_j(\eta), \lambda_{j-1} \leq \eta < \lambda_j\}. \end{aligned}$$

By the same argument on $j = 2$, $(u(\xi, \eta), l(\eta))$ is a unique solution to Problem 2.1.

Finally, we shall show the sequence $\{\lambda_j\}_{j=1}^\infty$ goes to infinity. Once we show this, for any $T > 0$, a pair of functions (u, l) which is a solution to Problem 2.1 can be constructed. To this end, *assume the contrary*. Then, $\{\lambda_j\}_{j=1}^\infty$ converges to some constant $\lambda_\infty < \infty$. Then, it follows from the definitions

$$\begin{aligned} &\lambda_{j+2} - \lambda_{j+1} \\ &= 4 \int_{\lambda_j}^{\lambda_{j+1}} \frac{\psi'_{j+1}(s)^2}{Q^2(s)} ds \\ &= 4 \int_{\lambda_j}^{\lambda_{j+1}} \frac{1}{Q^2(s)} \left\{ f'(s - l_0) + \frac{Q^2(l_j^{-1}(s - 2l_0))}{4\psi'_j(l_j^{-1}(s - 2l_0))} \right\}^2 ds \\ &\geq 4 \int_{\lambda_j}^{\lambda_{j+1}} \frac{1}{Q^2(s)} \left\{ \frac{Q^2(l_j^{-1}(s - 2l_0))}{4\psi_j(l_j^{-1}(s - 2l_0))} \right\}^2 ds. \end{aligned}$$

Using the change of variable $y = l_j^{-1}(s - 2l_0)$, we have

$$\lambda_{j+2} - \lambda_{j+1} \geq \int_{\lambda_{j-1}}^{\lambda_j} \frac{Q^2(y)}{Q^2(l_j(y + 2l_0))} dy.$$

From (A.5) there exists a constant δ such that Q is a monotone function on $[\lambda_\infty - \delta, \lambda_\infty)$. Let $\lambda_{j_0} \in \{\lambda_j\}_{j=1}^\infty$ be the lowest number which is in $[\lambda_\infty - \delta, \lambda_\infty)$. Here, we have two cases to consider.

(Case 1) Q is decreasing on $[\lambda_\infty - \delta, \lambda_\infty)$.

It holds

$$\frac{Q^2(\bar{\lambda})}{Q^2(l_j(\bar{\lambda}) + 2l_0)} \geq 1 \quad \text{for } \bar{\lambda} \in [\lambda_{j_0}, \lambda_\infty).$$

Therefore, we obtain

$$\lambda_{j+2} - \lambda_{j+1} \geq \int_{\lambda_{j-1}}^{\lambda_j} dy = \lambda_j - \lambda_{j-1}, \quad \text{and } \lim_{j \rightarrow \infty} \lambda_j = \infty.$$

It contradicts our assumption. In this case the proof completes.

(Case 2) Q is increasing on $[\lambda_\infty - \delta, \lambda_\infty)$.

From mean value theorem for integral, there exists a sequence $\bar{\lambda}_j \in [\lambda_{j-1}, \lambda_j]$ such that

$$(2.3) \quad \lambda_{j+2} - \lambda_{j+1} \geq \int_{\lambda_{j-1}}^{\lambda_j} \frac{Q^2(y)}{Q^2(l_j(y) + 2l_0)} dy = (\lambda_j - \lambda_{j-1})q_j,$$

where $q_j = \frac{Q^2(\bar{\lambda}_j)}{Q^2(l_j(\bar{\lambda}_j) + 2l_0)}$. By using (2.3) inductively, it follows that

$$\lambda_{j_0+2j} - \lambda_{j_0+2j-1} \geq (\lambda_{j_0+2} - \lambda_{j_0+1}) \sum_{k=1}^{j-1} q_{j_0+2} \cdots q_{j_0+2k},$$

$$\lambda_{j_0+2j-1} - \lambda_{j_0+2j-2} \geq (\lambda_{j_0+1} - \lambda_{j_0}) \sum_{k=1}^{j-1} q_{j_0+2} \cdots q_{j_0+2k-1}.$$

Hence, we have

$$(2.4) \quad \begin{aligned} & \lambda_\infty - \lambda_{j_0} \\ &= \lim_{j \rightarrow \infty} \{(\lambda_{j_0+1} - \lambda_{j_0}) + \cdots + (\lambda_{j_0+2j} - \lambda_{j_0+2j-1})\} \\ &\geq (\lambda_{j_0+1} - \lambda_{j_0}) \sum_{k=1}^{j-1} q_{j_0+1} \cdots q_{j_0+2k-1} \\ &\quad + (\lambda_{j_0+2} - \lambda_{j_0+1}) \sum_{k=1}^{j-1} q_{j_0+2} \cdots q_{j_0+2k}. \end{aligned}$$

From the assumption $\lambda_\infty < \infty$, the right hand side of (2.4) converges. Therefore, it implies that

$$(2.5) \quad \lim_{j \rightarrow \infty} q_{j_0+1} \cdots q_{j_0+2j-1} = 0 \text{ and } \lim_{j \rightarrow \infty} q_{j_0+2} \cdots q_{j_0+2j} = 0.$$

Let $\{M_j\}$ and $\{m_j\}$ be recurrences such that

$$M_j = \max_{\eta \in [\lambda_{j-1}, \lambda_j]} Q(\eta) \text{ and } m_j = \min_{\eta \in [\lambda_{j-1}, \lambda_j]} Q(\eta).$$

Then, because of $Q^2(l_j(\bar{\lambda}_j) + 2l_0) = \frac{Q^2(\bar{\lambda}_j)}{q_j}$, it holds $M_{j+1}^2 \geq \frac{m_j^2}{q_j}$. Since Q is increasing, $m_{j+1}^2 = M_j^2$ holds. Then we obtain

$$\begin{aligned} m_{j+1}^2 &= M_j^2 \geq \frac{m_{j-1}^2}{q_{j-1}} \\ &= \frac{1}{q_{j-1}} M_{j-2}^2 \geq \frac{1}{q_{j-1}} \frac{m_{j-3}^2}{q_{j-3}} \\ &\quad \dots \\ &\geq \frac{m_{j_0+1}^2}{q_{j-1} \cdots q_{j_0+1}} \text{ or } \frac{m_{j_0+2}^2}{q_{j-1} \cdots q_{j_0+2}}. \end{aligned}$$

On the other hand, it implies from (2.5) that $\lim_{j \rightarrow \infty} m_{j+1}^2 = \infty$. This contradicts the fact that Q is a continuous function and proves our assertion. ■

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